

1. Tu, 5.1

Let A and B be two points not on the real line \mathbb{R} . Consider the set $S = (\mathbb{R} \setminus \{0\}) \cup \{A, B\}$.

For any two positive real numbers c, d , define

$$I_A(-c, d) = (-c, 0) \cup \{A\} \cup (0, d)$$

and similarly for $I_B(-c, d)$, with B instead of A . Define a topology on S as follows: On $(\mathbb{R} \setminus \{0\})$, use the subspace topology inherited from \mathbb{R} , with open intervals as a basis. A basis at A is the set $\{I_A(-c, d) | c, d > 0\}$; similarly, a basis at B is $\{I_B(-c, d) | c, d > 0\}$.

(a) Prove that the map $h : I_A(-c, d) \rightarrow (-c, d)$ defined by

$$\begin{aligned} h(x) &= x \text{ for } x \in (-c, 0) \cup (0, d) \\ h(A) &= 0, \end{aligned}$$

is a homeomorphism.

Solution. First, a useful definition,

Definition. A function $f : X \rightarrow Y$ between two topological spaces (X, T_X) and (Y, T_Y) is a *homeomorphism* if

- f is a bijection,
- f is continuous,
- f^{-1} is continuous.

Clearly, h is a bijection, since h^{-1} is a function, where h^{-1} is defined as follows

$$h^{-1}(y) = \begin{cases} y & y \in (-c, 0) \cup (0, d) \\ A & y = 0 \end{cases}$$

Now, is h continuous? Yes, because the limit from the right or left of h at 0 is 0, precisely what $h(A)$ is defined to be. Finally, is h^{-1} continuous? Check this via the definition: Is the pullback of an open set from $(-c, d)$ under h^{-1} open in the topology generated on $I_A(-c, d)$? Consider the set $(-c, d)$ itself. This set is open in the topology on \mathbb{R} with pullback $I_A(-c, d)$. Because we are given that the set of all such I_A forms a basis at A , we can conclude that $I_A(-c, d)$ is open and h^{-1} is a continuous map at A . Continuity at all other points follows immediately from the definition of h^{-1} . \square

(b) Show that S is locally Euclidean and second countable, but not Hausdorff.

Solution. Locally Euclidean follows from above; since we have shown that at each point $p \in S$ there is a neighborhood U where a homeomorphism exists taking U to an open subset of \mathbb{R} . Here, we need to utilize the construction of bases at A and B in (a). Second countable is easy as well; we just need to construct a countable basis for S . Here it is

$$\begin{aligned} B_n &= \begin{cases} (-1/n, 0) \cup \{A\} \cup (0, 1/n) & n \text{ even} \\ (-1/n, 0) \cup \{B\} \cup (0, 1/n) & n \text{ odd} \end{cases} \\ \mathcal{B} &= \{B_n | n \in \mathbb{N}\} \end{aligned}$$

Now, I want to show that it fails to be Hausdorff. Assume that S is Hausdorff. This would mean that I can find open sets in the topology on S s.t. for $A \in U$ and $B \in V$, $U \cap V = \emptyset$. However, from the definition of the bases at A and B , such a construction is not possible, as there will be overlap of the open intervals defined around A, B . Therefore the intersection of U and V will be non-empty. Hence, S cannot be Hausdorff. \square

2. Tu, 6.6

Show that a map $f : M \rightarrow N$ of manifolds is C^∞ if and only if for every chart (U, ϕ) in the atlas of M and (V, ψ) in the atlas of N , the composite $\psi \circ f \circ \phi^{-1}$ is C^∞ on $\phi(f^{-1}(V) \cap U)$.

Solution. (\Leftarrow) Assume that for every chart (U, ϕ) in the atlas of M and (V, ψ) in the atlas of N , the composite $\psi \circ f \circ \phi^{-1}$ is C^∞ on $\phi(f^{-1}(V) \cap U)$. The pullback of V into M clearly contains p and therefore, by Definition 6.3, f is C^∞ at p . This argument can be extended to all points q in the intersection $f^{-1}(V) \cap U$ for all open sets $U \in M$ and $V \in N$. The collection of all such open sets comprises the spaces M and N . Therefore, $f : M \rightarrow N$ is a C^∞ map.

(\Rightarrow) Assume that a map $f : M \rightarrow N$ of manifolds is C^∞ . This means that for each point p in M there are charts (U, ϕ) containing $p \in M$ and (V, ψ) containing $f(p) \in N$ s.t. the map $\psi \circ f \circ \phi^{-1}$ is C^∞ at p . By continuity of f , a set U can always be chosen s.t. $f(U) \subset V$. This ensures that the composite map $\psi \circ f \circ \phi^{-1}$ will be C^∞ at all points q in the intersection of $f^{-1}(V) \cap U = U$. Because f is C^∞ for all points $p \in M$, the argument extends to all charts at all points $q \in M$ and $f(q) \in N$. Therefore, every chart (U, ϕ) in the atlas of M and (V, ψ) in the atlas of N , the composite $\psi \circ f \circ \phi^{-1}$ is C^∞ on $\phi(f^{-1}(V) \cap U)$. \square

3. Tu, 6.7

Show that the general linear group $\text{GL}(n, \mathbb{R})$ defined in Example 5.14 is a Lie group under matrix multiplication.

Solution. Clearly, the product of matrices with non-zero determinant is itself a matrix with non-zero determinant. So, $\text{GL}(n, \mathbb{R})$ is closed under matrix multiplication.

Component-wise, matrix multiplication is defined by, for elements $A, B \in \text{GL}(n, \mathbb{R})$,

$$(AB)_{ij} = \sum_{k=1}^n a_{ik}b_{kj}.$$

This is a polynomial in the coordinates of both A, B , therefore matrix multiplication is C^∞ .

Now, it remains to show that the inverse map is C^∞ . From Cramer's rule, we know that

$$(A^{-1})_{ij} = \frac{1}{\det A} (-1)^{j+i} ((j, i) - \text{minor of } A),$$

where the (j, i) -minor of a matrix is defined as the determinant of the submatrix obtained from the deletion of the j^{th} row and the i^{th} column of A . This map is C^∞ as long as the $\det A \neq 0$, but this is guaranteed in $\text{GL}(n, \mathbb{R})$.

Therefore, $\text{GL}(n, \mathbb{R})$ is closed under matrix multiplication with both the multiplication and inverse maps C^∞ . Therefore $\text{GL}(n, \mathbb{R})$ is a Lie group. \square

4. Tu, 6.8

Let V be a finite-dimensional vector space over \mathbb{R} , and $\text{GL}(V)$ the group of all linear isomorphisms of V itself. A basis e_1, \dots, e_n for V induces a bijection

$$\begin{aligned} \text{GL}(n, \mathbb{R}) &\rightarrow \text{GL}(V), \\ [a_j^i] &\mapsto (e_j \mapsto \sum_i a_j^i e_i), \end{aligned}$$

making $\text{GL}(V)$ into a C^∞ manifold, which we denote temporarily by $\text{GL}(V)_e$. If $\text{GL}(V)_u$ is the manifold structure induced from another basis u_1, \dots, u_n for V , show that $\text{GL}(V)_e$ is diffeomorphic to $\text{GL}(V)_u$.

Solution. To show that the two smooth manifolds are diffeomorphic, it is natural to try to find a suitable diffeomorphism. In this instance, the most natural such diffeomorphism would be the identity map. That is, take a vector $v = \sum_j c_j e_j \in \text{GL}(V)_e$ and map it to itself in $\text{GL}(V)_u$. Clearly, the identity map is a diffeomorphism, but is this map reasonable here?

Since we are considering the action of all linear operations (with non-zero determinant) on a vector space V , this is a suitable map from $\text{GL}(V)_e$ to $\text{GL}(V)_u$; i.e. there will always be a linear transformation that, when the change of basis formula has been taken into account, will create the same vector in $\text{GL}(V)_u$ that is in $\text{GL}(V)_e$. In this case, the choice of basis provides us with the capability of putting a C^∞ manifold structure on a vector space. However, the specific basis that we use is not important; it is only important that we have a basis. Therefore, for any choice of basis, the identity map will always provide a diffeomorphism.

Therefore, $\text{GL}(V)_e$ is diffeomorphic to $\text{GL}(V)_u$. \square

5. Tu, 7.1

Suppose a left action of a topological group G on a topological space S is continuous; this simply means that the map $G \times S \rightarrow S$ describing the action is continuous. Define two points of x, y of S to be equivalent if there is a $g \in G$ such that $y = gx$. Let $G \backslash S$ be the quotient space. Prove that the projection map $\pi : S \rightarrow G \backslash S$ is an open map.

Solution. To show that the projection map π is open, I need to show that $\pi^{-1}(\pi(U))$ is open in S . Take an arbitrary open set $U \in S$,

$$\begin{aligned}\pi^{-1}(\pi(U)) &= \bigcup_{y \in U} [y] \\ &= \bigcup_{g \in G} gU.\end{aligned}$$

For any $g \in G$, multiplication by g creates a homeomorphism on S . Therefore, the set gU is open in S . Since a topological space is closed under arbitrary union, $\bigcup_{g \in G} gU$ is open. Therefore, π is an open map. \square

6. Tu, 7.3

Show that the real projective space $\mathbb{R}P^n$ is compact. (*Hint:* Use Exercise 7.11).

Solution. If I can show that $\mathbb{R}P^n$ is homeomorphic to something which is compact, then it would follow that $\mathbb{R}P^n$ is compact.

The hint given is to use Exercise 7.11, which provides a map that would induce a homeomorphism on S^n / \sim , which is compact. So, to finish this problem, I need to complete Exercise 7.11.

7.11 Prove that the map $f : \mathbb{R}^{n+1} \setminus \{0\} \rightarrow S^n$ given by

$$f(x) = \frac{x}{|x|}$$

induces a homeomorphism $\bar{f} : \mathbb{R}P^n \rightarrow S^n / \sim$. (*Hint:* Find an inverse map

$$\bar{g} : S^n / \sim \rightarrow \mathbb{R}P^n$$

and show that both \bar{f} and \bar{g} are continuous.)

Proof. Define $\bar{f} : \mathbb{R}P^n \rightarrow S^n / \sim$ by $\bar{f}([x]) = \left[\frac{x}{|x|} \right] \in S^n / \sim$. This map is well defined because $\bar{f}([tx]) = \left[\frac{tx}{|tx|} \right] = \left[\frac{x}{|x|} \right]$ are the projection maps to the quotient spaces. By Proposition 7.1, \bar{f} is continuous because $\pi_2 \circ f$ is continuous.

Now define $g : S^n \rightarrow \mathbb{R}^{n+1} \setminus \{0\}$ by $g(x) = x$. This map induces another map $\bar{g} : S^n / \sim \rightarrow \mathbb{R}P^n$, $\bar{g}([x]) = [x]$. From above, \bar{g} is well defined and continuous. Additionally,

$$\begin{aligned}\bar{g} \circ \bar{f}([x]) &= \left[\frac{x}{|x|} \right] = [x] \\ \bar{f} \circ \bar{g}([x]) &= [x],\end{aligned}$$

So, \bar{f} is continuous with continuous inverse $\bar{f}^{-1} = \bar{g}$. Therefore, \bar{f} is a homeomorphism from $\mathbb{R}P^n$ to S^n / \sim .

Therefore, $\mathbb{R}P^n$ is homeomorphic to the compact S^n / \sim and $\mathbb{R}P^n$ is hence compact. \square

7. Use the Inverse Function Theorem to do Problem 1.4 with $F(x)$ replaced by $x + F(x)$.

Solution. Define the map $F : B(0, \pi/2) \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ by

$$F(x) = \begin{cases} x + h(|x|)\frac{x}{|x|} & \text{for } x \neq 0 \\ 0 & \text{for } x = 0. \end{cases}$$

We know that h is a diffeomorphism on $\mathbb{R}^+ \setminus \{0\}$, therefore we don't need to worry about differentiability of F, F^{-1} due to h, h^{-1} . The problem is that F^{-1} , as was previously defined in the book is not differentiable at 0. If we can add differentiability at 0 for F^{-1} , we are done. However, adding x we can use the Implicit Function Theorem to show that F^{-1} is differentiable at 0. If I can show that the determinant of the Jacobian of F is nonzero at 0, then F will be locally invertible at 0, meaning F^{-1} is C^∞ at 0. The determinant of the Jacobian is $\prod_{i=1}^n \partial F / \partial x^i |_{x=0} = \prod_{i=1}^n (1 + (h(|x|)x/|x|)_i) |_{x=0}$, which will be nonzero since all partial derivatives $(h(|x|)x/|x|)_i |_{x=0}$ will be positive semi-definite.

Therefore, F is a diffeomorphism. \square